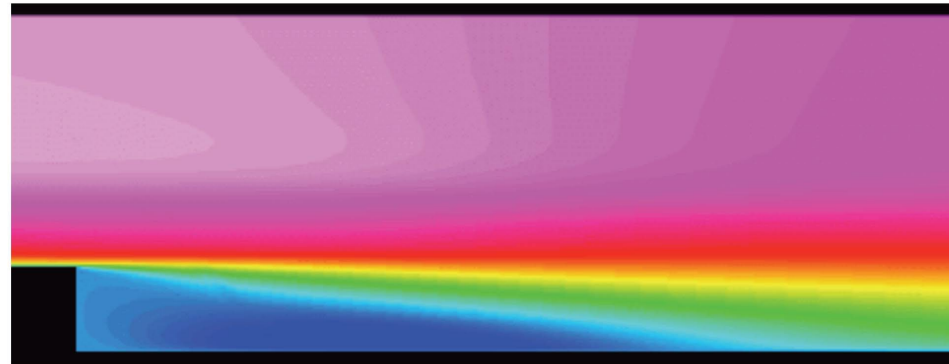


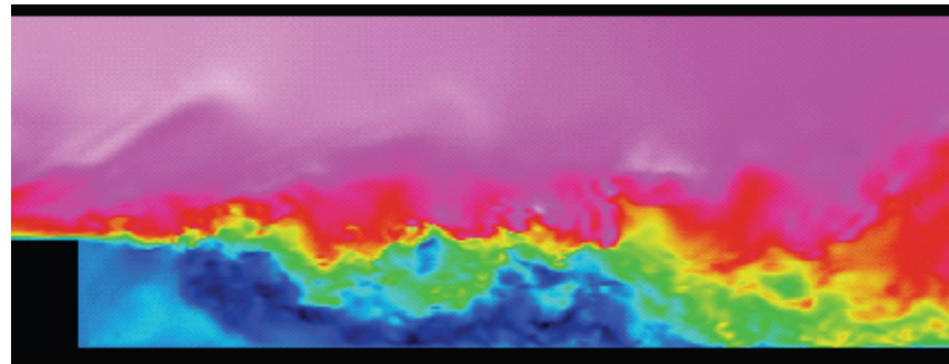
Steady and unsteady flow

Steady-state



Source: Rémy Fransen, 3rd INCA colloquium, ONERA, Toulouse (2011)

Unsteady



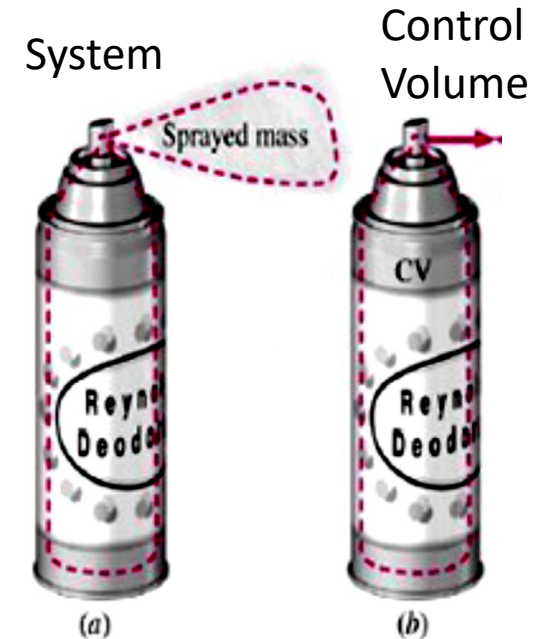
Source: Rémy Fransen, 3rd INCA colloquium, ONERA, Toulouse (2011)

Exercise 3.

- Reynolds Transport Theorem (RTT)
 - Integral relations for a control volume
 - One of the most fundamental theorems in fluid mechanics
 - From the theorem we get fundamental laws:
 - Mass conservation (continuity)
 - Linear momentum conservation (impulse)
 - Angular momentum conservation
 - Energy conservation
 - These expressions are the foundation of the Navier-Stokes equations, chapter 4.
- RTT allows us to analyse a system over a control volume

Exercise 3.

- **System:** Collection of materia with a fixed identity
 - Always the same atoms or fluid particles
 - A specific, and identifiable quantity of mass
- **Control volume (CV):** A fixed volume in space
 - Fluid flow through the CV
 - Geometrically constraint
 - Independent of mass



Exercise 3.

- **RTT:**

$$\frac{d}{dt}(B_{\text{syst}}) = \frac{d}{dt}\left(\int_{\text{CV}} \beta \rho \, dV\right) + \int_{\text{CS}} \beta \rho (\tilde{v}_r \circ \tilde{n}) \, dA \quad \text{Eq. (3.16)}$$

Change of B in the whole system	Change of B inside the CV	B “flowing” in and out of the CV
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- By letting B equal mass, linear momentum, angular momentum, or energy, we get the four laws
- B is an **extensive** property and has units e.g. [kg], [kg m/s]...
- β is an **intensive** property, i.e. amount of B per unit mass, with units of [kg/kg], [kg m/s² /kg]...

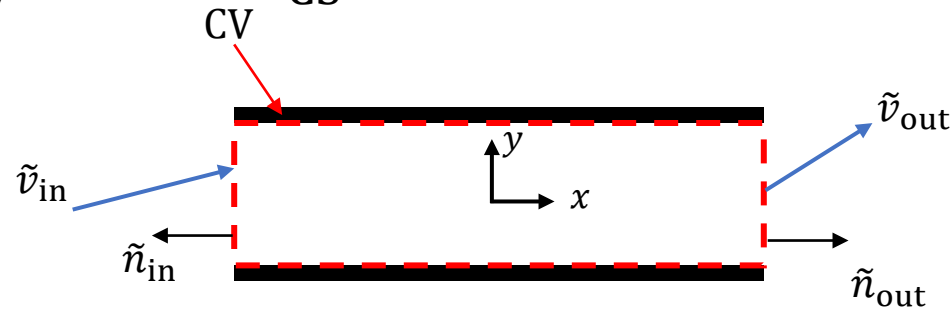
$$\beta = \frac{dB}{dm}$$

- For RTT to be true, the system and the CV must equal at the time t , $\text{syst}=\text{CV}$, $B_{\text{syst}}(t) = B_{\text{CV}}(t)$
 - At $t + dt$: $B_{\text{syst}}(t + dt) = B_{\text{CV}}(t + dt) - (\text{inflow of } B)_{\text{CS}} + (\text{outflow of } B)_{\text{CS}}$
 - RTT can predict the change inside the CV at all times after t

Exercise 3.

- Setting $B = \text{mass} \rightarrow$ mass conservation and assume steady-state (3.20)

$$\frac{d}{dt}(m) = 0 = \frac{d}{dt} \left(\int_{CV} \rho \, dV \right) + \int_{CS} \rho (\tilde{v}_r \circ \tilde{n}) \, dA \Rightarrow [\text{steady}] \Rightarrow \int_{CS} \rho (\tilde{v} \circ \tilde{n}) \, dA = 0$$



$$\tilde{v}_{\text{in}} = \begin{bmatrix} u_{\text{in}} \\ v_{\text{in}} \end{bmatrix}, \quad \tilde{n}_{\text{in}} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\tilde{v}_{\text{out}} = \begin{bmatrix} u_{\text{out}} \\ v_{\text{out}} \end{bmatrix}, \quad \tilde{n}_{\text{out}} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

- 1D mass conservation yield:

$$\sum_i (\rho_i A_i V_i)_{\text{in}} = \sum_j (\rho_j A_j V_j)_{\text{out}} \quad (3.24)$$

$$\dot{m}_{\text{in}} = \dot{m}_{\text{out}} \quad (3.27)$$