# Compressible Flow - TME085 

## Lecture 11

Niklas Andersson

Chalmers University of Technology<br>Department of Mechanics and Maritime Sciences<br>Division of Fluid Mechanics<br>Gothenburg, Sweden<br>niklas.andersson@chalmers.se

Chapter 7
Unsteady Wave Motion


## Learning Outcomes

3 Describe typical engineering flow situations in which compressibility effects are more or less predominant (e.g. Mach number regimes for steady-state flows)
4 Present at least two different formulations of the governing equations for compressible flows and explain what basic conservation principles they are based on
8 Derive (marked) and apply (all) of the presented mathematical formulae for classical gas dynamics
a 1D isentropic flow*
—b normal shocks*
Eij unsteady waves and discontinuities in 1D
K basic acoustics
9 Solve engineering problems involving the above-mentioned phenomena (8a-8k)
11 Explain how the equations for aero-acoustics and classical acoustics are derived as limiting cases of the compressible flow equations moving normal shocks - frame of reference seems to be the key here?!

## Roadmap - Unsteady Wave Motion



Chapter 7.3
Reflected Shock Wave

## One-Dimensional Flow with Friction

what happens when a moving shock approaches a wall?

## Shock Reflection



## Shock Reflection - Particle Path

A fluid particle located at $x_{0}$ at time $t_{0}$ (a location ahead of the shock) will be affected by the moving shock and follow the blue path

| time | location | velocity |
| :---: | :---: | :---: |
| $t_{0}$ | $x_{0}$ | 0 |
| $t_{1}$ | $x_{0}$ | $u_{p}$ |
| $t_{2}$ | $x_{1}$ | $u_{p}$ |
| $t_{3}$ | $x_{1}$ | 0 |



## Shock Reflection Relations

- velocity ahead of reflected shock: $W_{r}+u_{p}$
- velocity behind reflected shock: $W_{r}$

Continuity:

$$
\rho_{2}\left(W_{r}+u_{p}\right)=\rho_{5} W_{r}
$$

Momentum:

$$
p_{2}+\rho_{2}\left(W_{r}+u_{p}\right)^{2}=p_{5}+\rho_{5} W_{r}^{2}
$$

Energy:

$$
h_{2}+\frac{1}{2}\left(W_{r}+u_{p}\right)^{2}=h_{5}+\frac{1}{2} W_{r}^{2}
$$

## Shock Reflection Relations

Reflected shock is determined such that $u_{5}=0$

$$
\frac{M_{r}}{M_{r}^{2}-1}=\frac{M_{s}}{M_{s}^{2}-1} \sqrt{1+\frac{2(\gamma-1)}{(\gamma+1)^{2}}\left(M_{s}^{2}-1\right)\left(\gamma+\frac{1}{M_{s}^{2}}\right)}
$$

where

$$
M_{r}=\frac{W_{r}+u_{p}}{a_{2}}
$$

## Tailored v.s. Non-Tailored Shock Reflection

- The time duration of condition 5 is determined by what happens after interaction between reflected shock and contact discontinuity
- For special choice of initial conditions (tailored case), this interaction is negligible, thus prolonging the duration of condition 5


## Tailored v.s. Non-Tailored Shock Reflection

Under-tailored conditions:



Mach number of incident wave lower than in tailored conditions
Over-tailored conditions:
Mach number of incident wave higher than in tailored conditions

## Shock Reflection - Example

$\underset{\text { (Example } 7.1 \text { in Anderson) }}{\text { Shock }}$ in shock tube $(\gamma=1.4)$

Incident shock (given data)

$$
\begin{array}{cl}
p_{2} / p_{1} & 10.0 \\
M_{s} & 2.95 \\
T_{2} / T_{1} & 2.623 \\
p_{1} & 1.0[\mathrm{bar}] \\
T_{1} & 300.0[\mathrm{~K}]
\end{array}
$$

Calculated data

$$
\begin{array}{cl}
M_{r} & 2.09 \\
p_{5} / p_{2} & 4.978 \\
T_{5} / T_{2} & 1.77
\end{array}
$$

$$
\begin{aligned}
p_{5} & =\left(\frac{p_{5}}{p_{2}}\right)\left(\frac{p_{2}}{p_{1}}\right) p_{1}=49.78 \\
T_{5} & =\left(\frac{T_{5}}{T_{2}}\right)\left(\frac{T_{2}}{T_{1}}\right) T_{1}=1393
\end{aligned}
$$

## Shock Reflection - Shock Tube

- Very high pressure and temperature conditions in a specified location with very high precision $\left(p_{5}, T_{5}\right)$
- measurements of thermodynamic properties of various gases at extreme conditions, e.g. dissociation energies, molecular relaxation times, etc.
$\rightarrow$ measurements of chemical reaction properties of various gas mixtures at extreme conditions


## Roadmap - Unsteady Wave Motion



The Shock Tube

## Shock Tube


tube with closed ends
diaphragm inside, separating two different constant states
(could also be two different gases)
if diaphragm is removed suddenly (by inducing a breakdown) the two states come into contact and a flow develops
assume that $p_{4}>p_{1}$ :
state 4 is "driver" section
state 1 is "driven" section

## Shock Tube


flow at some time after diaphragm breakdown

## Shock Tube



## Shock Tube

- As the diaphragm is removed, a pressure discontinuity is generated
- The only process that can generate a pressure difference in the gas is a shock
- The velocity upstream of the shock must be supersonic
- Since the gas is standing still when the shock tube is started, the shock must move in order to establish a relative velocity
- The shock must move in to the gas with the lower pressure


## Shock Tube

- By using light gases for the driver section (e.g. He) and heavier gases for the driven section (e.g. air) the pressure $p_{4}$ required for a specific $p_{2} / p_{1}$ ratio is significantly reduced
- If $T_{4} / T_{1}$ is increased, the pressure $p_{4}$ required for a specific $p_{2} / p_{1}$ is also reduced


## Roadmap - Unsteady Wave Motion



Chapter 7.5
Elements of Acoustic Theory

## Sound Waves

## sound wave

Weakest audible sound wave Loud sound wave
Amplified music
Jet engine @ 30 m
Threshold of pain
Military jet @ 30 m
$L_{p}[\mathrm{~dB}] \quad \Delta \mathrm{p}[\mathrm{Pa}]$
$02.83 \times 10^{-5}$
$91 \quad 1$
12028
13090
140283
150890

## Example:

$\Delta p \sim 1$ Pa gives $\Delta \rho \sim 8.5 \times 10^{-6} \mathrm{~kg} / \mathrm{m}^{3}$ and $\Delta u \sim 2.4 \times 10^{-3} \mathrm{~m} / \mathrm{s}$

## Elements of Acoustic Theory

PDE:s for conservation of mass and momentum are derived in Chapter 6:

|  | conservation form | non-conservation form |
| :---: | :---: | :---: |
| mass | $\frac{\partial \rho}{\partial t}+\nabla \cdot(\rho \mathbf{v})=0$ | $\frac{D \rho}{D t}+\rho(\nabla \cdot \mathbf{v})=0$ |
| momentum | $\frac{\partial}{\partial t}(\rho \mathbf{v})+\nabla \cdot(\rho \mathbf{v} \mathbf{v}+p \mathbf{I})=0$ | $\rho \frac{D \mathbf{v}}{D t}+\nabla p=0$ |

## Elements of Acoustic Theory

For adiabatic inviscid flow we also have the entropy equation as

$$
\frac{D s}{D t}=0
$$

Assume one-dimensional flow

$$
\left.\begin{array}{l}
\rho=\rho(x, t) \\
\mathbf{v}=u(x, t) \mathbf{e}_{x} \\
p=p(x, t) \\
\ldots
\end{array}\right\} \Rightarrow \quad \begin{array}{ll}
\text { continuity } & \frac{\partial \rho}{\partial t}+u \frac{\partial \rho}{\partial x}+\rho \frac{\partial u}{\partial x}=0 \\
\text { momentum } & \rho \frac{\partial u}{\partial t}+\rho u \frac{\partial u}{\partial x}+\frac{\partial p}{\partial x}=0 \\
s=\text { constant }
\end{array}
$$

can $\frac{\partial p}{\partial x}$ be expressed in terms of density?

## Elements of Acoustic Theory

From Chapter 1: any thermodynamic state variable is uniquely defined by any tow other state variables

$$
p=p(\rho, s) \Rightarrow d p=\left(\frac{\partial p}{\partial \rho}\right)_{s} d \rho+\left(\frac{\partial p}{\partial s}\right)_{\rho} d s
$$

$s=$ constant gives

$$
\begin{gathered}
d p=\left(\frac{\partial p}{\partial \rho}\right)_{s} d \rho=a^{2} d \rho \\
\Rightarrow\left\{\begin{array}{l}
\frac{\partial \rho}{\partial t}+u \frac{\partial \rho}{\partial x}+\rho \frac{\partial u}{\partial x}=0 \\
\rho \frac{\partial u}{\partial t}+\rho u \frac{\partial u}{\partial x}+a^{2} \frac{\partial \rho}{\partial x}=0
\end{array}\right.
\end{gathered}
$$

## Elements of Acoustic Theory

Assume small perturbations around stagnant reference condition:

$$
\rho=\rho_{\infty}+\Delta \rho \quad p=p_{\infty}+\Delta p \quad T=T_{\infty}+\Delta T \quad u=u_{\infty}+\Delta u=\left\{u_{\infty}=0\right\}=\Delta u
$$

where $\rho_{\infty}, p_{\infty}$, and $T_{\infty}$ are constant
Now, insert $\rho=\left(\rho_{\infty}+\Delta \rho\right)$ and $u=\Delta u$ in the continuity and momentum equations (derivatives of $\rho_{\infty}$ are zero)

$$
\Rightarrow\left\{\begin{array}{l}
\frac{\partial}{\partial t}(\Delta \rho)+\Delta u \frac{\partial}{\partial x}(\Delta \rho)+\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial x}(\Delta u)=0 \\
\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial t}(\Delta u)+\left(\rho_{\infty}+\Delta \rho\right) \Delta u \frac{\partial}{\partial x}(\Delta u)+a^{2} \frac{\partial}{\partial x}(\Delta \rho)=0
\end{array}\right.
$$

## Elements of Acoustic Theory

Assume small perturbations around stagnant reference condition:

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Now, insert $\rho=\left(\rho_{\infty}+\Delta \rho\right)$ and $u=\Delta u$ in the continuity and momentum equations (derivatives of $\rho_{\infty}$ are zero)

$$
\Rightarrow\left\{\begin{array}{l}
\frac{\partial}{\partial t}(\Delta \rho)+\Delta u \frac{\partial}{\partial x}(\Delta \rho)+\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial x}(\Delta u)=0 \\
\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial t}(\Delta u)+\left(\rho_{\infty}+\Delta \rho\right) \Delta u \frac{\partial}{\partial x}\left(\Delta u+a^{2} \frac{\partial}{\partial x}(\Delta \rho)=0\right.
\end{array}\right.
$$

## Elements of Acoustic Theory

Speed of sound is a thermodynamic state variable $\Rightarrow a^{2}=a^{2}(\rho, s)$. With entropy constant $\Rightarrow a^{2}=a^{2}(\rho)$

Taylor expansion around $\mathrm{a}_{\infty}$ with ( $\Delta \rho=\rho-\rho_{\infty}$ ) gives

$$
\begin{gathered}
a^{2}=a_{\infty}^{2}+\left(\frac{\partial}{\partial \rho}\left(a^{2}\right)\right)_{\infty} \Delta \rho+\frac{1}{2}\left(\frac{\partial^{2}}{\partial \rho^{2}}\left(a^{2}\right)\right)_{\infty}(\Delta \rho)^{2}+\ldots \\
\Rightarrow\left\{\begin{array}{l}
\frac{\partial}{\partial \hat{\partial}}(\Delta \rho)+\Delta u \frac{\partial}{\partial x}(\Delta \rho)+\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial x}(\Delta u)=0 \\
\left(\rho_{\infty}+\Delta \rho\right) \frac{\partial}{\partial t}(\Delta u)+\left(\rho_{\infty}+\Delta \rho\right) \Delta u \frac{\partial}{\partial x}(\Delta u)+\left[a_{\infty}^{2}+\left(\frac{\partial}{\partial \rho}\left(a^{2}\right)\right)_{\infty} \Delta \rho+\ldots\right] \frac{\partial}{\partial x}(\Delta \rho)=0
\end{array}\right.
\end{gathered}
$$

## Elements of Acoustic Theory - Acoustic Equations

Since $\Delta \rho$ and $\Delta u$ are assumed to be small $\left(\Delta \rho \ll \rho_{\infty}, \Delta u \ll a\right)$

- products of perturbations can be neglected
- higher-order terms in the Taylor expansion can be neglected

$$
\Rightarrow\left\{\begin{array}{l}
\frac{\partial}{\partial t}(\Delta \rho)+\rho_{\infty} \frac{\partial}{\partial x}(\Delta u)=0 \\
\rho_{\infty} \frac{\partial}{\partial t}(\Delta u)+a_{\infty}^{2} \frac{\partial}{\partial x}(\Delta \rho)=0
\end{array}\right.
$$

Note! Only valid for small perturbations (sound waves)

This type of derivation is based on linearization, i.e. the acoustic equations are linear

Elements of Acoustic Theory - Acoustic Equations

Acoustic equations:
"... describe the motion of gas induced by the passage of a sound wave ..."

## Elements of Acoustic Theory - Wave Equation

Combining linearized continuity and the momentum equations we get

$$
\frac{\partial^{2}}{\partial t^{2}}(\Delta \rho)=a_{\infty}^{2} \frac{\partial^{2}}{\partial x^{2}}(\Delta \rho)
$$

(combine the time derivative of the continuity eqn. and the divergence of the momentum eqn.)
General solution:

$$
\Delta \rho(x, t)=F\left(x-a_{\infty} t\right)+G\left(x+a_{\infty} t\right)
$$

wave traveling in positive $x$-direction with speed $a_{\infty}$
wave traveling in negative $x$-direction with speed $a_{\infty}$
$F$ and $G$ may be arbitrary functions
Wave shape is determined by functions $F$ and $G$

## Elements of Acoustic Theory - Wave Equation

Spatial and temporal derivatives of $F$ are obtained according to

$$
\left\{\begin{array}{l}
\frac{\partial F}{\partial t}=\frac{\partial F}{\partial\left(x-a_{\infty} t\right)} \frac{\partial\left(x-a_{\infty} t\right)}{\partial t}=-a_{\infty} F^{\prime} \\
\frac{\partial F}{\partial x}=\frac{\partial F}{\partial\left(x-a_{\infty} t\right)} \frac{\partial\left(x-a_{\infty} t\right)}{\partial x}=F^{\prime}
\end{array}\right.
$$

spatial and temporal derivatives of G can of course be obtained in the same way...

## Elements of Acoustic Theory - Wave Equation

with $\Delta \rho(x, t)=F\left(x-a_{\infty} t\right)+G\left(x+a_{\infty} t\right)$ and the derivatives of $F$ and $G$ we get

$$
\frac{\partial^{2}}{\partial t^{2}}(\Delta \rho)=a_{\infty}^{2} F^{\prime \prime}+a_{\infty}^{2} G^{\prime \prime}
$$

and

$$
\frac{\partial^{2}}{\partial x^{2}}(\Delta \rho)=F^{\prime \prime}+G^{\prime \prime}
$$

which gives

$$
\frac{\partial^{2}}{\partial t^{2}}(\Delta \rho)-a_{\infty}^{2} \frac{\partial^{2}}{\partial x^{2}}(\Delta \rho)=0
$$

i.e., the proposed solution fulfils the wave equation

## Elements of Acoustic Theory - Wave Equation

$F$ and $G$ may be arbitrary functions, assume $G=0$

$$
\Delta \rho(x, t)=F\left(x-a_{\infty} t\right)
$$

If $\Delta \rho$ is constant (constant wave amplitude), $\left(x-a_{\infty} t\right)$ must be a constant which implies

$$
x=a_{\infty} t+c
$$

where c is a constant

$$
\frac{d x}{d t}=a_{\infty}
$$

## Elements of Acoustic Theory - Wave Equation

We want a relation between $\Delta \rho$ and $\Delta u$
$\Delta \rho(x, t)=F\left(x-a_{\infty} t\right)$ (wave in positive $x$ direction) gives:

$$
\frac{\partial}{\partial t}(\Delta \rho)=-a_{\infty} F^{\prime}
$$

$$
\frac{\partial}{\partial x}(\Delta \rho)=F^{\prime}
$$

$$
\underbrace{\frac{\partial}{\partial t}(\Delta \rho)}_{-a_{\infty} F^{\prime}}+a_{\infty} \underbrace{\frac{\partial}{\partial x}(\Delta \rho)}_{F^{\prime}}=0
$$

$$
\begin{gathered}
\text { or } \\
\frac{\partial}{\partial x}(\Delta \rho)=-\frac{1}{a_{\infty}} \frac{\partial}{\partial t}(\Delta \rho)
\end{gathered}
$$

## Elements of Acoustic Theory - Wave Equation

Linearized momentum equation:

$$
\begin{gathered}
\rho_{\infty} \frac{\partial}{\partial t}(\Delta u)=-a_{\infty}^{2} \frac{\partial}{\partial x}(\Delta \rho) \Rightarrow \\
\frac{\partial}{\partial t}(\Delta u)=-\frac{a_{\infty}^{2}}{\rho_{\infty}} \frac{\partial}{\partial x}(\Delta \rho)=\left\{\frac{\partial}{\partial x}(\Delta \rho)=-\frac{1}{a_{\infty}} \frac{\partial}{\partial t}(\Delta \rho)\right\}=\frac{a_{\infty}}{\rho_{\infty}} \frac{\partial}{\partial t}(\Delta \rho) \\
\frac{\partial}{\partial t}\left(\Delta u-\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho\right)=0 \Rightarrow \Delta u-\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho=\mathrm{const}
\end{gathered}
$$

In undisturbed gas $\Delta u=\Delta \rho=0$ which implies that the constant must be zero and thus

$$
\Delta u=\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho
$$

## Elements of Acoustic Theory - Wave Equation

Similarly, for $\Delta \rho(x, t)=G\left(x+a_{\infty} t\right)$ (wave in negative $x$ direction) we obtain:

$$
\Delta u=-\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho
$$

Also, since $\Delta p=a_{\infty}^{2} \Delta \rho$ we get:
Right going wave $(+x$ direction $) \quad \Delta u=\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho=\frac{1}{a_{\infty} \rho_{\infty}} \Delta \rho$
Left going wave (-x direction) $\Delta u=-\frac{a_{\infty}}{\rho_{\infty}} \Delta \rho=-\frac{1}{a_{\infty} \rho_{\infty}} \Delta p$

## Elements of Acoustic Theory - Wave Equation

$\Delta \Delta u$ denotes induced mass motion and is positive in the positive $x$-direction

$$
\Delta u= \pm \frac{a_{\infty} \Delta \rho}{\rho_{\infty}}= \pm \frac{\Delta p}{a_{\infty} \rho_{\infty}}
$$

- condensation (the part of the sound wave where $\Delta \rho>0$ ):
$\Delta u$ is always in the same direction as the wave motion
$>$ rarefaction (the part of the sound wave where $\Delta \rho<0$ ):
$\Delta u$ is always in the opposite direction as the wave motion


## Elements of Acoustic Theory - Wave Equation Summary

Combining linearized continuity and the momentum equations we get

$$
\frac{\partial^{2}}{\partial t^{2}}(\Delta \rho)=a_{\infty}^{2} \frac{\partial^{2}}{\partial x^{2}}(\Delta \rho)
$$

- Due to the assumptions made, the equation is not exact
- More and more accurate as the perturbations becomes smaller and smaller
- How should we describe waves with larger amplitudes?


## Roadmap - Unsteady Wave Motion



Chapter 7.6
Finite (Non-Linear) Waves

## Finite (Non-Linear) Waves

When $\Delta \rho, \Delta u, \Delta \rho, \ldots$ Become large, the linearized acoustic equations become poor approximations

Non-linear equations must be used
One-dimensional non-linear continuity and momentum equations

$$
\begin{aligned}
& \frac{\partial \rho}{\partial t}+u \frac{\partial \rho}{\partial x}+\rho \frac{\partial u}{\partial x}=0 \\
& \frac{\partial u}{\partial t}+u \frac{\partial u}{\partial x}+\frac{1}{\rho} \frac{\partial p}{\partial x}=0
\end{aligned}
$$

## Finite (Non-Linear) Waves

We still assume isentropic flow, $d s=0$

$$
\frac{\partial \rho}{\partial t}=\left(\frac{\partial \rho}{\partial p}\right)_{s} \frac{\partial p}{\partial t}=\frac{1}{a^{2}} \frac{\partial p}{\partial t}
$$

$$
\frac{\partial \rho}{\partial x}=\left(\frac{\partial \rho}{\partial p}\right)_{s} \frac{\partial p}{\partial x}=\frac{1}{a^{2}} \frac{\partial p}{\partial x}
$$

Inserted in the continuity equation this gives:

$$
\begin{aligned}
& \frac{\partial p}{\partial t}+u \frac{\partial p}{\partial x}+\rho a^{2} \frac{\partial u}{\partial x}=0 \\
& \frac{\partial u}{\partial t}+u \frac{\partial u}{\partial x}+\frac{1}{\rho} \frac{\partial p}{\partial x}=0
\end{aligned}
$$

## Finite (Non-Linear) Waves

Add $1 /(\rho a)$ times the continuity equation to the momentum equation:

$$
\left[\frac{\partial u}{\partial t}+(u+a) \frac{\partial u}{\partial x}\right]+\frac{1}{\rho a}\left[\frac{\partial p}{\partial t}+(u+a) \frac{\partial p}{\partial x}\right]=0
$$

If we instead subtraction $1 /(\rho a)$ times the continuity equation from the momentum equation, we get:

$$
\left[\frac{\partial u}{\partial t}+(u-a) \frac{\partial u}{\partial x}\right]-\frac{1}{\rho a}\left[\frac{\partial p}{\partial t}+(u-a) \frac{\partial p}{\partial x}\right]=0
$$

## Finite (Non-Linear) Waves

Since $u=u(x, t)$, we have:

$$
d u=\frac{\partial u}{\partial t} d t+\frac{\partial u}{\partial x} d x=\frac{\partial u}{\partial t} d t+\frac{\partial u}{\partial x} \frac{d x}{d t} d t
$$

$$
\text { Let } \frac{d x}{d t}=u+a \text { gives }
$$

$$
d u=\left[\frac{\partial u}{\partial t}+(u+a) \frac{\partial u}{\partial x}\right] d t
$$

Interpretation: change of $u$ in the direction of line $\frac{d x}{d t}=u+a$

Finite (Non-Linear) Waves

In the same way we get:

$$
d p=\frac{\partial p}{\partial t} d t+\frac{\partial p}{\partial x} \frac{d x}{d t} d t
$$

and thus

$$
d p=\left[\frac{\partial p}{\partial t}+(u+a) \frac{\partial p}{\partial x}\right] d t
$$

## Finite (Non-Linear) Waves

Now, if we combine

$$
\begin{gathered}
{\left[\frac{\partial u}{\partial t}+(u+a) \frac{\partial u}{\partial x}\right]+\frac{1}{\rho a}\left[\frac{\partial p}{\partial t}+(u+a) \frac{\partial p}{\partial x}\right]=0} \\
d u=\left[\frac{\partial u}{\partial t}+(u+a) \frac{\partial u}{\partial x}\right] d t \\
d p=\left[\frac{\partial p}{\partial t}+(u+a) \frac{\partial p}{\partial x}\right] d t
\end{gathered}
$$

we get

$$
\frac{d u}{d t}+\frac{1}{\rho a} \frac{d p}{d t}=0
$$

## Characteristic Lines

Thus, along a line $d x=(u+a) d t$ we have

$$
d u+\frac{d p}{\rho a}=0
$$

In the same way we get along a line where $d x=(u-a) d t$

$$
d u-\frac{d p}{\rho a}=0
$$

## Characteristic Lines

- We have found a path through a point $\left(x_{1}, t_{1}\right)$ along which the governing partial differential equations reduces to ordinary differential equations
- These paths or lines are called characteristic lines
- The $C^{+}$and $C^{-}$characteristic lines are physically the paths of right- and left-running sound waves in the $x t$-plane


## Characteristic Lines



## Characteristic Lines - Summary

$$
\begin{array}{ll}
\frac{d u}{d t}+\frac{1}{\rho a} \frac{d p}{d t}=0 & \text { along } C^{+} \text {characteristic } \\
\frac{d u}{d t}-\frac{1}{\rho a} \frac{d p}{d t}=0 & \text { along } C^{-} \text {characteristic }
\end{array}
$$

$$
\begin{array}{ll}
d u+\frac{d p}{\rho a}=0 & \\
\text { along } C^{+} \text {characteristic } \\
d u-\frac{d p}{\rho a}=0 & \text { along } C^{-} \text {characteristic }
\end{array}
$$

## Riemann Invariants

Integration gives:

$$
\begin{aligned}
& J^{+}=u+\int \frac{d p}{\rho a}=\text { constant along } C^{+} \text {characteristic } \\
& J^{-}=u-\int \frac{d p}{\rho a}=\text { constant along } C^{-} \text {characteristic }
\end{aligned}
$$

We need to rewrite $\frac{d p}{\rho a}$ to be able to perform the integrations

## Riemann Invariants

Let's consider an isentropic processes:

$$
p=c_{1} T^{\gamma /(\gamma-1)}=c_{2} a^{2 \gamma /(\gamma-1)}
$$

where $c_{1}$ and $c_{2}$ are constants and thus

$$
d p=c_{2}\left(\frac{2 \gamma}{\gamma-1}\right) a^{[2 \gamma /(\gamma-1)-1]} d a
$$

Assume calorically perfect gas: $\mathrm{a}^{2}=\frac{\gamma p}{\rho} \Rightarrow \rho=\frac{\gamma p}{a^{2}}$
with $p=c_{2} a^{2 \gamma /(\gamma-1)}$ we get $\rho=c_{2} \gamma a^{[2 \gamma /(\gamma-1)-2]}$

Riemann Invariants

$$
J^{+}=u+\int \frac{d p}{\rho a}=u+\int \frac{c_{2}\left(\frac{2 \gamma}{\gamma-1}\right) a^{[2 \gamma /(\gamma-1)-1]}}{c_{2} \gamma a^{[2 \gamma /(\gamma-1)-1]}} d a=u+\int \frac{2 d a}{\gamma-1}
$$

$$
\begin{aligned}
J^{+} & =u+\frac{2 a}{\gamma-1} \\
J^{-} & =u-\frac{2 a}{\gamma-1}
\end{aligned}
$$

## Riemann Invariants

If $J^{+}$and $J^{-}$are known at some point $(x, t)$, then

$$
\left\{\begin{array} { l } 
{ J ^ { + } + J ^ { - } = 2 u } \\
{ J ^ { + } - J ^ { - } = \frac { 4 a } { \gamma - 1 } }
\end{array} \Rightarrow \left\{\begin{array}{l}
u=\frac{1}{2}\left(J^{+}+J^{-}\right) \\
a=\frac{\gamma-1}{4}\left(J^{+}-J^{-}\right)
\end{array}\right.\right.
$$

Flow state is uniquely defined!

## Method of Characteristics



## Summary

Acoustic waves

- $\Delta \rho, \Delta u$, etc - very small
- All parts of the wave propagate with the same velocity $a_{\infty}$
- The wave shape stays the same The flow is governed by linear relations

Finite (non-linear) waves

- $\Delta \rho, \Delta u$, etc - can be large
- Each local part of the wave propagates at the local velocity $(u+a)$
- The wave shape changes with time
- The flow is governed by non-linear relations


## One-Dimensional Flow with Friction

the method of characteristics is a central element in classic compressible flow theory

