### Compressible Flow - TME085 Lecture 11

Niklas Andersson

Chalmers University of Technology Department of Mechanics and Maritime Sciences Division of Fluid Mechanics Gothenburg, Sweden

niklas.andersson@chalmers.se





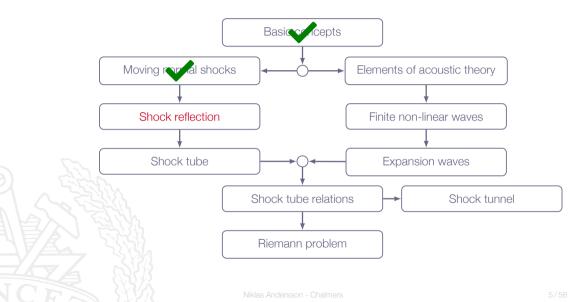
# Chapter 7 Unsteady Wave Motion



## Learning Outcomes

- 3 Describe typical engineering flow situations in which compressibility effects are more or less predominant (e.g. Mach number regimes for steady-state flows)
- 4 **Present** at least two different formulations of the governing equations for compressible flows and **explain** what basic conservation principles they are based on
- 8 Derive (marked) and apply (all) of the presented mathematical formulae for classical gas dynamics
  - a 1D isentropic flow\*
  - b normal shocks\*
    - unsteady waves and discontinuities in 1D
    - basic acoustics
  - Solve engineering problems involving the above-mentioned phenomena (8a-8k)
  - Explain how the equations for aero-acoustics and classical acoustics are derived as limiting cases of the compressible flow equations
    - moving normal shocks frame of reference seems to be the key here?!

#### Roadmap - Unsteady Wave Motion



## Chapter 7.3 Reflected Shock Wave

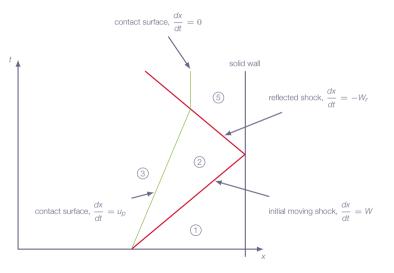
Niklas Andersson - Chalmers

#### One-Dimensional Flow with Friction

#### what happens when a moving shock approaches a wall?

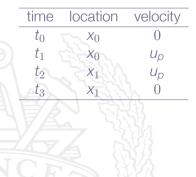


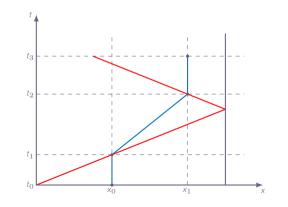
### Shock Reflection



#### Shock Reflection - Particle Path

A fluid particle located at  $x_0$  at time  $t_0$  (a location ahead of the shock) will be affected by the moving shock and follow the blue path





#### Shock Reflection Relations

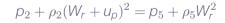
- ► velocity ahead of reflected shock:  $W_r + u_p$
- $\blacktriangleright$  velocity behind reflected shock:  $W_r$

Continuity:

 $\rho_2(W_r + u_p) = \rho_5 W_r$ 

Momentum:

Energy:



$$h_2 + \frac{1}{2}(W_r + u_p)^2 = h_5 + \frac{1}{2}W_r^2$$

Niklas Andersson - Chalmers

#### Shock Reflection Relations

Reflected shock is determined such that  $u_5 = 0$ 

$$\frac{M_r}{M_r^2 - 1} = \frac{M_s}{M_s^2 - 1} \sqrt{1 + \frac{2(\gamma - 1)}{(\gamma + 1)^2} (M_s^2 - 1) \left(\gamma + \frac{1}{M_s^2}\right)}$$

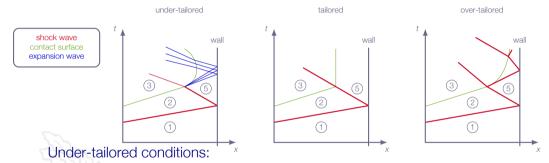


$$M_r = \frac{W_r + u_p}{a_2}$$

#### Tailored v.s. Non-Tailored Shock Reflection

- The time duration of condition 5 is determined by what happens after interaction between reflected shock and contact discontinuity
- For special choice of initial conditions (tailored case), this interaction is negligible, thus prolonging the duration of condition 5

### Tailored v.s. Non-Tailored Shock Reflection



Mach number of incident wave lower than in tailored conditions

#### Over-tailored conditions:

Mach number of incident wave higher than in tailored conditions

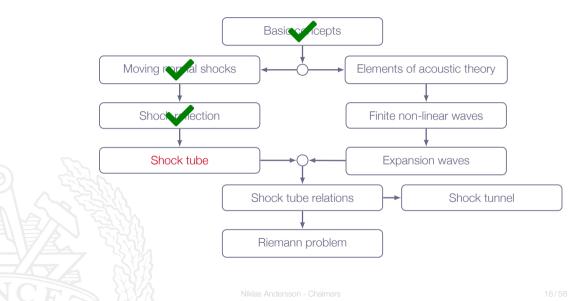
#### Shock Reflection - Example

Shock reflection in shock tube ( $\gamma=1.4$ ) (Example 7.1 in Anderson)

Incident shock (given data) Calculated data  $M_r$  2.09  $p_2/p_1$ 10.0  $p_5/p_2$  4.978 Ms 2.95  $T_5/T_2$  1.77  $T_2/T_1$  2.623 1.0 [bar]  $p_1$  $T_1$ 300.0 [K]  $\rho_5 = \left(\frac{\rho_5}{\rho_2}\right) \left(\frac{\rho_2}{\rho_1}\right) \rho_1 = 49.78$  $T_5 = \left(\frac{T_5}{T_2}\right) \left(\frac{T_2}{T_1}\right) T_1 = 1393$ 

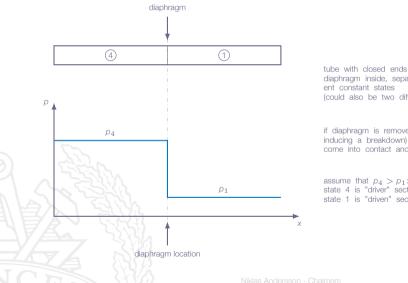
- ► Very high pressure and temperature conditions in a specified location with very high precision (p<sub>5</sub>, T<sub>5</sub>)
  - measurements of thermodynamic properties of various gases at extreme conditions, *e.g.* dissociation energies, molecular relaxation times, etc.
    - measurements of chemical reaction properties of various gas mixtures at extreme conditions

#### Roadmap - Unsteady Wave Motion



## The Shock Tube

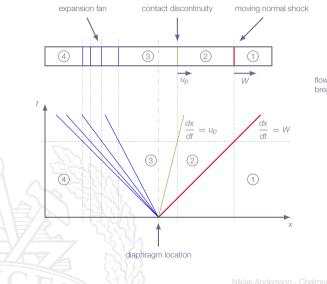




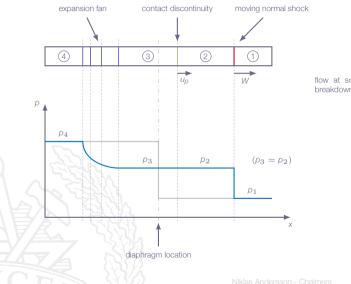
diaphragm inside, separating two different constant states (could also be two different gases)

if diaphragm is removed suddenly (by inducing a breakdown) the two states come into contact and a flow develops

assume that  $p_4 > p_1$ : state 4 is "driver" section state 1 is "driven" section



flow at some time after diaphragm breakdown



flow at some time after diaphragm breakdown

► As the diaphragm is removed, a pressure discontinuity is generated

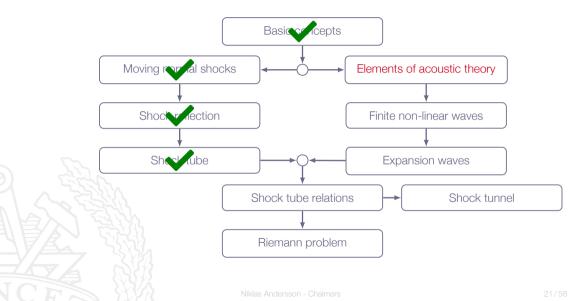
- ▶ The only process that can generate a pressure difference in the gas is a shock
- ▶ The velocity upstream of the shock must be supersonic

Since the gas is standing still when the shock tube is started, the shock must move in order to establish a relative velocity

The shock must move in to the gas with the lower pressure

- By using light gases for the driver section (e.g. He) and heavier gases for the driven section (e.g. air) the pressure p<sub>4</sub> required for a specific p<sub>2</sub>/p<sub>1</sub> ratio is significantly reduced
- ► If  $T_4/T_1$  is increased, the pressure  $p_4$  required for a specific  $p_2/p_1$  is also reduced

#### Roadmap - Unsteady Wave Motion



# Chapter 7.5 Elements of Acoustic Theory



#### Sound Waves

sound wave	$L_p$ [dB]	$\Delta \rho$ [Pa]
Weakest audible sound wave	0	$2.83 \times 10^{-5}$
Loud sound wave	91	1
Amplified music	120	28
Jet engine @ 30 m	130	90
Threshold of pain	140	283
Military jet @ 30 m	150	890

Example:

 $\Delta \rho \sim$  1 Pa gives  $\Delta \rho \sim 8.5 \times 10^{-6}$  kg/m<sup>3</sup> and  $\Delta u \sim 2.4 \times 10^{-3}$  m/s

#### PDE:s for conservation of mass and momentum are derived in Chapter 6:

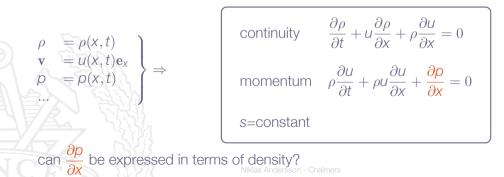
	conservation form	non-conservation form
mass	$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$	$\frac{D\rho}{Dt} + \rho(\nabla \cdot \mathbf{v}) = 0$
momentum	$\frac{\partial}{\partial t}(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \mathbf{v} + \rho \mathbf{I}) = 0$	$\rho \frac{D\mathbf{v}}{Dt} + \nabla \rho = 0$



For adiabatic inviscid flow we also have the entropy equation as

 $\frac{Ds}{Dt} = 0$ 

#### Assume one-dimensional flow



From Chapter 1: any thermodynamic state variable is uniquely defined by any tow other state variables

$$p = p(\rho, s) \Rightarrow dp = \left(\frac{\partial p}{\partial \rho}\right)_s d\rho + \left(\frac{\partial p}{\partial s}\right)_\rho ds$$

s=constant gives

$$dp = \left(\frac{\partial p}{\partial \rho}\right)_{s} d\rho = a^{2} d\rho$$



$$\Rightarrow \begin{cases} \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} = 0\\ \rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + a^2 \frac{\partial \rho}{\partial x} = 0 \end{cases}$$

Niklas Andersson - Chalmers

Assume small perturbations around stagnant reference condition:

 $\rho = \rho_{\infty} + \Delta \rho \qquad p = p_{\infty} + \Delta p \qquad T = T_{\infty} + \Delta T \qquad u = u_{\infty} + \Delta u = \{u_{\infty} = 0\} = \Delta u$ 

where  $\rho_{\infty}$ ,  $p_{\infty}$ , and  $T_{\infty}$  are constant

Now, insert  $\rho = (\rho_{\infty} + \Delta \rho)$  and  $u = \Delta u$  in the continuity and momentum equations (derivatives of  $\rho_{\infty}$  are zero)

$$\Rightarrow \begin{cases} \frac{\partial}{\partial t} (\Delta \rho) + \Delta u \frac{\partial}{\partial x} (\Delta \rho) + (\rho_{\infty} + \Delta \rho) \frac{\partial}{\partial x} (\Delta u) = 0 \\ (\rho_{\infty} + \Delta \rho) \frac{\partial}{\partial t} (\Delta u) + (\rho_{\infty} + \Delta \rho) \Delta u \frac{\partial}{\partial x} (\Delta u) + a^2 \frac{\partial}{\partial x} (\Delta \rho) = 0 \end{cases}$$

Assume small perturbations around stagnant reference condition:

 $\rho = \rho_{\infty} + \Delta \rho \qquad p = p_{\infty} + \Delta p \qquad T = T_{\infty} + \Delta T \qquad u = u_{\infty} + \Delta u = \{u_{\infty} = 0\} = \Delta u$ 

where  $\rho_{\infty}$ ,  $p_{\infty}$ , and  $T_{\infty}$  are constant

Now, insert  $\rho = (\rho_{\infty} + \Delta \rho)$  and  $u = \Delta u$  in the continuity and momentum equations (derivatives of  $\rho_{\infty}$  are zero)

$$\Rightarrow \begin{cases} \frac{\partial}{\partial t} (\Delta \rho) + \Delta u \frac{\partial}{\partial x} (\Delta \rho) + (\rho_{\infty} + \Delta \rho) \frac{\partial}{\partial x} (\Delta u) = 0\\ (\rho_{\infty} + \Delta \rho) \frac{\partial}{\partial t} (\Delta u) + (\rho_{\infty} + \Delta \rho) \Delta u \frac{\partial}{\partial x} (\Delta u) + a^{2} \frac{\partial}{\partial x} (\Delta \rho) = 0 \end{cases}$$

Speed of sound is a thermodynamic state variable  $\Rightarrow a^2 = a^2(\rho, s)$ . With entropy constant  $\Rightarrow a^2 = a^2(\rho)$ 

Taylor expansion around  $a_{\infty}$  with  $(\Delta \rho = \rho - \rho_{\infty})$  gives

$$\begin{aligned} \mathbf{a}^{2} &= \mathbf{a}_{\infty}^{2} + \left(\frac{\partial}{\partial\rho}(\mathbf{a}^{2})\right)_{\infty} \Delta\rho + \frac{1}{2} \left(\frac{\partial^{2}}{\partial\rho^{2}}(\mathbf{a}^{2})\right)_{\infty} (\Delta\rho)^{2} + \dots \\ \begin{cases} \frac{\partial}{\partial t}(\Delta\rho) + \Delta u \frac{\partial}{\partial x}(\Delta\rho) + (\rho_{\infty} + \Delta\rho) \frac{\partial}{\partial x}(\Delta u) = 0\\ (\rho_{\infty} + \Delta\rho) \frac{\partial}{\partial t}(\Delta u) + (\rho_{\infty} + \Delta\rho) \Delta u \frac{\partial}{\partial x}(\Delta u) + \left[a_{\infty}^{2} + \left(\frac{\partial}{\partial\rho}(a^{2})\right)_{\infty} \Delta\rho + \dots\right] \frac{\partial}{\partial x}(\Delta\rho) = 0 \end{aligned}$$

#### Elements of Acoustic Theory - Acoustic Equations

Since  $\Delta \rho$  and  $\Delta u$  are assumed to be small ( $\Delta \rho \ll \rho_{\infty}$ ,  $\Delta u \ll a$ )

- products of perturbations can be neglected
- ▶ higher-order terms in the Taylor expansion can be neglected

$$\Rightarrow \begin{cases} \frac{\partial}{\partial t}(\Delta\rho) + \rho_{\infty}\frac{\partial}{\partial x}(\Delta u) = 0\\ \rho_{\infty}\frac{\partial}{\partial t}(\Delta u) + a_{\infty}^{2}\frac{\partial}{\partial x}(\Delta\rho) = 0 \end{cases}$$

Note! Only valid for small perturbations (sound waves)

This type of derivation is based on linearization, *i.e.* the acoustic equations are linear

#### Elements of Acoustic Theory - Acoustic Equations

Acoustic equations:

"... describe the motion of gas induced by the passage of a sound wave ..."

#### Elements of Acoustic Theory - Wave Equation

Combining linearized continuity and the momentum equations we get

$$\boxed{\frac{\partial^2}{\partial t^2}(\Delta \rho) = a_\infty^2 \frac{\partial^2}{\partial x^2}(\Delta \rho)}$$

(combine the time derivative of the continuity eqn. and the divergence of the momentum eqn.)

General solution:

$$\Delta \rho(x,t) = F(x - a_{\infty}t) + G(x + a_{\infty}t)$$

wave traveling in positive *x*-direction with speed  $a_{\infty}$ 

wave traveling in negative *x*-direction with speed  $a_{\infty}$ 

F and G may be arbitrary functions

Wave shape is determined by functions F and G

#### Elements of Acoustic Theory - Wave Equation

Spatial and temporal derivatives of F are obtained according to

$$\frac{\partial F}{\partial t} = \frac{\partial F}{\partial (x - a_{\infty} t)} \frac{\partial (x - a_{\infty} t)}{\partial t} = -a_{\infty} F'$$
$$\frac{\partial F}{\partial x} = \frac{\partial F}{\partial (x - a_{\infty} t)} \frac{\partial (x - a_{\infty} t)}{\partial x} = F'$$

spatial and temporal derivatives of G can of course be obtained in the same way...

#### Elements of Acoustic Theory - Wave Equation

with  $\Delta \rho(x,t) = F(x - a_{\infty}t) + G(x + a_{\infty}t)$  and the derivatives of *F* and *G* we get

$$\frac{\partial^2}{\partial t^2}(\Delta\rho) = a_\infty^2 F'' + a_\infty^2 G''$$

and

$$\frac{\partial^2}{\partial x^2}(\Delta \rho) = F'' + G''$$

which gives

$$\frac{\partial^2}{\partial t^2}(\Delta \rho) - a_{\infty}^2 \frac{\partial^2}{\partial x^2}(\Delta \rho) = 0$$

i.e., the proposed solution fulfils the wave equation

Niklas Andersson - Chalmers

*F* and *G* may be arbitrary functions, assume G = 0

 $\Delta \rho(\mathbf{x}, t) = F(\mathbf{x} - \mathbf{a}_{\infty} t)$ 

If  $\Delta \rho$  is constant (constant wave amplitude),  $(x - a_{\infty}t)$  must be a constant which implies

where *c* is a constant

$$x = a_{\infty}t + c$$

 $\frac{dx}{dt} = a_{\infty}$ 

We want a relation between  $\Delta \rho$  and  $\Delta u$ 

 $\Delta \rho(x,t) = F(x - a_{\infty}t)$  (wave in positive *x* direction) gives:

 $\frac{\partial}{\partial t}(\Delta \rho) = -a_{\infty}F'$  and  $\frac{\partial}{\partial x}(\Delta \rho) = F'$ 

$$\underbrace{\frac{\partial}{\partial t}(\Delta \rho)}_{-a_{\infty}F'} + a_{\infty} \underbrace{\frac{\partial}{\partial x}(\Delta \rho)}_{F'} = 0$$



or

 $\frac{\partial}{\partial \mathbf{x}}(\Delta \rho) = -\frac{1}{a} \frac{\partial}{\partial t}(\Delta \rho)$ 

Linearized momentum equation:

$$\rho_{\infty}\frac{\partial}{\partial t}(\Delta u) = -a_{\infty}^{2}\frac{\partial}{\partial x}(\Delta \rho) \Rightarrow$$

$$\frac{\partial}{\partial t}(\Delta u) = -\frac{a_{\infty}^2}{\rho_{\infty}}\frac{\partial}{\partial x}(\Delta \rho) = \left\{\frac{\partial}{\partial x}(\Delta \rho) = -\frac{1}{a_{\infty}}\frac{\partial}{\partial t}(\Delta \rho)\right\} = \frac{a_{\infty}}{\rho_{\infty}}\frac{\partial}{\partial t}(\Delta \rho)$$

$$\frac{\partial}{\partial t} \left( \Delta u - \frac{a_{\infty}}{\rho_{\infty}} \Delta \rho \right) = 0 \Rightarrow \Delta u - \frac{a_{\infty}}{\rho_{\infty}} \Delta \rho = \text{const}$$

In undisturbed gas  $\Delta u = \Delta \rho = 0$  which implies that the constant must be zero and thus

$$\Delta u = \frac{a_{\infty}}{\rho_{\infty}} \Delta \rho$$

Similarly, for  $\Delta \rho(x,t) = G(x + a_{\infty}t)$  (wave in negative *x* direction) we obtain:

$$\Delta u = -\frac{a_{\infty}}{\rho_{\infty}}\Delta\rho$$

Also, since  $\Delta p = a_{\infty}^2 \Delta \rho$  we get:

Right going wave (+x direction) 
$$\Delta u = \frac{a_{\infty}}{\rho_{\infty}} \Delta \rho = \frac{1}{a_{\infty}\rho_{\infty}} \Delta \rho$$

Left going wave

(-x direction) 
$$\Delta u = -\frac{a_{\infty}}{\rho_{\infty}}\Delta \rho = -\frac{1}{a_{\infty}\rho_{\infty}}\Delta \rho$$

•  $\Delta u$  denotes induced mass motion and is positive in the positive x-direction

$$\Delta u = \pm \frac{a_{\infty} \Delta \rho}{\rho_{\infty}} = \pm \frac{\Delta \rho}{a_{\infty} \rho_{\infty}}$$

• condensation (the part of the sound wave where  $\Delta \rho > 0$ ):  $\Delta u$  is always in the same direction as the wave motion

rarefaction (the part of the sound wave where  $\Delta \rho < 0$ ):  $\Delta u$  is always in the opposite direction as the wave motion

Combining linearized continuity and the momentum equations we get

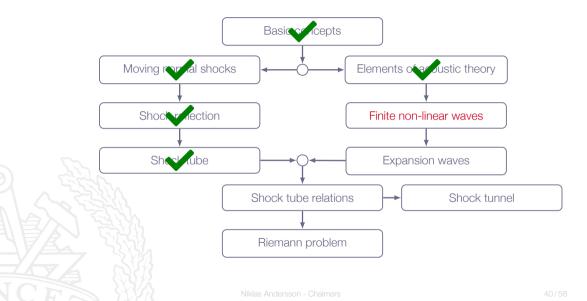
$$\boxed{\frac{\partial^2}{\partial t^2}(\Delta \rho) = a_{\infty}^2 \frac{\partial^2}{\partial x^2}(\Delta \rho)}$$

Due to the assumptions made, the equation is not exact

More and more accurate as the perturbations becomes smaller and smaller

How should we describe waves with larger amplitudes?

# Roadmap - Unsteady Wave Motion



# Chapter 7.6 Finite (Non-Linear) Waves



When  $\Delta \rho$ ,  $\Delta u$ ,  $\Delta p$ , ... Become large, the linearized acoustic equations become poor approximations

Non-linear equations must be used

One-dimensional non-linear continuity and momentum equations



$$\frac{\frac{\partial \rho}{\partial t} + u\frac{\partial \rho}{\partial x} + \rho\frac{\partial u}{\partial x} = 0}{\frac{\partial u}{\partial t} + u\frac{\partial u}{\partial x} + \frac{1}{\rho}\frac{\partial \rho}{\partial x} = 0}$$

We still assume isentropic flow, ds = 0

$$\frac{\partial \rho}{\partial t} = \left(\frac{\partial \rho}{\partial \rho}\right)_s \frac{\partial \rho}{\partial t} = \frac{1}{a^2} \frac{\partial \rho}{\partial t}$$

$$\frac{\partial \rho}{\partial x} = \left(\frac{\partial \rho}{\partial p}\right)_{s} \frac{\partial p}{\partial x} = \frac{1}{a^{2}} \frac{\partial p}{\partial x}$$

Inserted in the continuity equation this gives:



$$\frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + \rho a^2 \frac{\partial u}{\partial x} = 0$$
$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0$$

Add  $1/(\rho a)$  times the continuity equation to the momentum equation:

$$\left[\frac{\partial u}{\partial t} + (u+a)\frac{\partial u}{\partial x}\right] + \frac{1}{\rho a}\left[\frac{\partial p}{\partial t} + (u+a)\frac{\partial p}{\partial x}\right] = 0$$

If we instead subtraction  $1/(\rho a)$  times the continuity equation from the momentum equation, we get:

$$\left[\frac{\partial u}{\partial t} + (u-a)\frac{\partial u}{\partial x}\right] - \frac{1}{\rho a}\left[\frac{\partial p}{\partial t} + (u-a)\frac{\partial p}{\partial x}\right] = 0$$

Since u = u(x, t), we have:

$$du = \frac{\partial u}{\partial t}dt + \frac{\partial u}{\partial x}dx = \frac{\partial u}{\partial t}dt + \frac{\partial u}{\partial x}\frac{dx}{dt}dt$$

Let 
$$\frac{dx}{dt} = u + a$$
 gives  
$$du = \left[\frac{\partial u}{\partial t} + (u + a)\frac{\partial u}{\partial x}\right] dt$$

Interpretation: change of *u* in the direction of line  $\frac{dx}{dt} = u + a$ 

In the same way we get:

$$dp = \frac{\partial p}{\partial t}dt + \frac{\partial p}{\partial x}\frac{dx}{dt}dt$$

and thus

$$dp = \left[\frac{\partial p}{\partial t} + (u+a)\frac{\partial p}{\partial x}\right]dt$$

Now, if we combine

$$\begin{bmatrix} \frac{\partial u}{\partial t} + (u+a)\frac{\partial u}{\partial x} \end{bmatrix} + \frac{1}{\rho a} \begin{bmatrix} \frac{\partial p}{\partial t} + (u+a)\frac{\partial p}{\partial x} \end{bmatrix} = 0$$
$$du = \begin{bmatrix} \frac{\partial u}{\partial t} + (u+a)\frac{\partial u}{\partial x} \end{bmatrix} dt$$
$$dp = \begin{bmatrix} \frac{\partial p}{\partial t} + (u+a)\frac{\partial p}{\partial x} \end{bmatrix} dt$$
$$\begin{bmatrix} \frac{\partial u}{\partial t} + \frac{1}{\rho a}\frac{dp}{dt} = 0 \end{bmatrix}$$



#### **Characteristic Lines**

Thus, along a line dx = (u + a)dt we have

$$du + \frac{dp}{\rho a} = 0$$

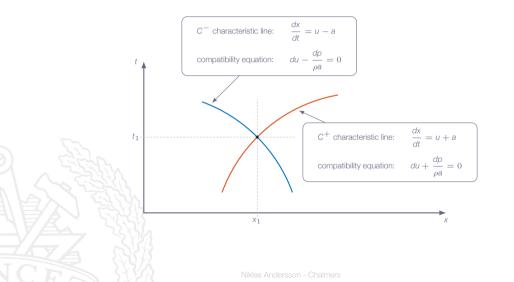
In the same way we get along a line where dx = (u - a)dt

$$du - \frac{dp}{\rho a} = 0$$

- We have found a path through a point  $(x_1, t_1)$  along which the governing partial differential equations reduces to ordinary differential equations
- ► These paths or lines are called characteristic lines

The  $C^+$  and  $C^-$  characteristic lines are physically the paths of right- and left-running sound waves in the *xt*-plane

## **Characteristic Lines**



# Characteristic Lines - Summary

$$\frac{du}{dt} + \frac{1}{\rho a} \frac{dp}{dt} = 0 \quad \text{along } C^+ \text{ characteristic}$$
$$\frac{du}{dt} - \frac{1}{\rho a} \frac{dp}{dt} = 0 \quad \text{along } C^- \text{ characteristic}$$

$$du + \frac{dp}{\rho a} = 0 \quad \text{along } C^+ \text{ characteristic}$$
$$du - \frac{dp}{\rho a} = 0 \quad \text{along } C^- \text{ characteristic}$$

## **Riemann Invariants**

Integration gives:

$$J^+ = u + \int \frac{dp}{\rho a} = \text{constant along } C^+ \text{ characteristic}$$
  
 $J^- = u - \int \frac{dp}{\rho a} = \text{constant along } C^- \text{ characteristic}$ 

We need to rewrite  $\frac{dp}{\rho a}$  to be able to perform the integrations

#### **Riemann Invariants**

Let's consider an isentropic processes:

$$\rho = c_1 T^{\gamma/(\gamma-1)} = c_2 a^{2\gamma/(\gamma-1)}$$

where  $c_1$  and  $c_2$  are constants and thus

$$d
ho = c_2 \left(rac{2\gamma}{\gamma-1}
ight) a^{[2\gamma/(\gamma-1)-1]} da$$

Assume calorically perfect gas:  $a^2 = \frac{\gamma \rho}{\rho} \Rightarrow \rho = \frac{\gamma \rho}{a^2}$ 

with  $\rho = c_2 a^{2\gamma/(\gamma-1)}$  we get  $\rho = c_2 \gamma a^{[2\gamma/(\gamma-1)-2]}$ 

# **Riemann Invariants**

$$J^{+} = u + \int \frac{dp}{\rho a} = u + \int \frac{C_{2}\left(\frac{2\gamma}{\gamma-1}\right)a^{[2\gamma/(\gamma-1)-1]}}{C_{2}\gamma a^{[2\gamma/(\gamma-1)-1]}}da = u + \int \frac{2da}{\gamma-1}$$



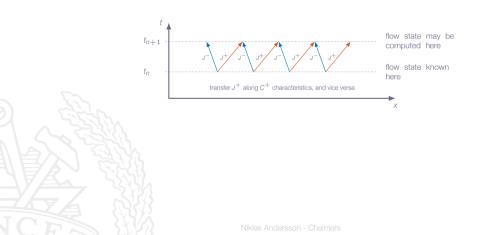
$$J^{+} = u + \frac{2a}{\gamma - 1}$$
$$J^{-} = u - \frac{2a}{\gamma - 1}$$

If  $J^+$  and  $J^-$  are known at some point (x, t), then

$$\begin{cases} J^{+} + J^{-} = 2u \\ J^{+} - J^{-} = \frac{4a}{\gamma - 1} \end{cases} \Rightarrow \begin{cases} u = \frac{1}{2}(J^{+} + J^{-}) \\ a = \frac{\gamma - 1}{4}(J^{+} - J^{-}) \end{cases}$$

Flow state is uniquely defined!

# Method of Characteristics



# Summary

#### Acoustic waves

- $\Delta \rho$ ,  $\Delta u$ , etc very small
- ► All parts of the wave propagate with the same velocity a<sub>∞</sub>
- The wave shape stays the same
- The flow is governed by linear relations

#### Finite (non-linear) waves

- $\Delta \rho$ ,  $\Delta u$ , etc can be large
- Each local part of the wave propagates at the local velocity (u + a)
- ► The wave shape changes with time
- The flow is governed by non-linear relations

# One-Dimensional Flow with Friction

#### the method of characteristics is a central element in classic compressible flow theory

