Compressible Flow - TME085 Lecture 8

Niklas Andersson

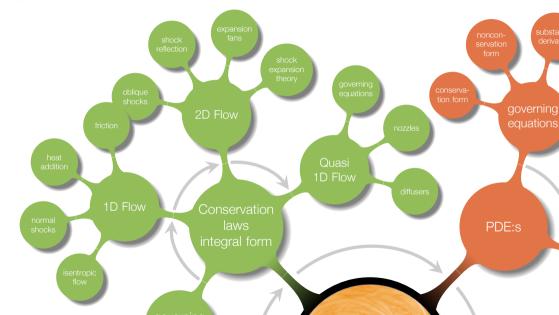
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Chapter 5 Quasi-One-Dimensional Flow

Overview

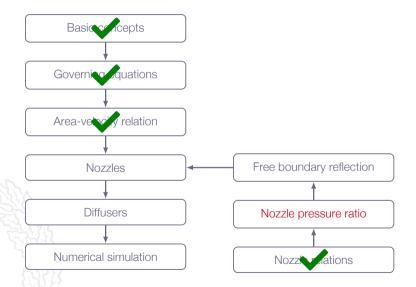


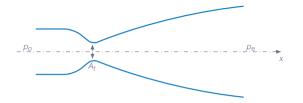
Learning Outcomes

- 4 Present at least two different formulations of the governing equations for compressible flows and explain what basic conservation principles they are based on
- 6 Define the special cases of calorically perfect gas, thermally perfect gas and real gas and explain the implication of each of these special cases
- 7 Explain why entropy is important for flow discontinuities
- 8 Derive (marked) and apply (all) of the presented mathematical formulae for classical gas dynamics
 - a 1D isentropic flow*
 - b normal shocks*
 - i detached blunt body shocks, nozzle flows
- 9 Solve engineering problems involving the above-mentioned phenomena (8a-8k)

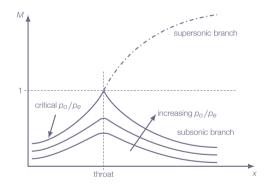
what does quasi-1D mean? either the flow is 1D or not, or?

Roadmap - Quasi-One-Dimensional Flow

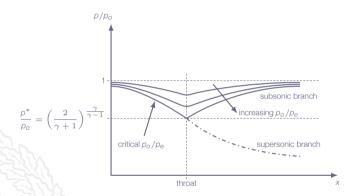




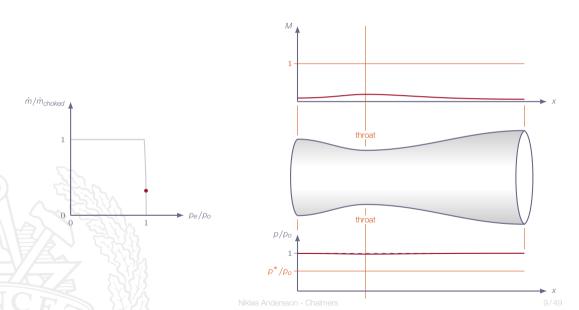
A(x) area function $A_t \quad \min\{A(x)\}$ $p_o \quad \text{inlet total pressure}$ $p_e \quad \text{outlet static pressure}$ (ambient pressure) $p_o/p_e \quad \text{pressure ratio}$

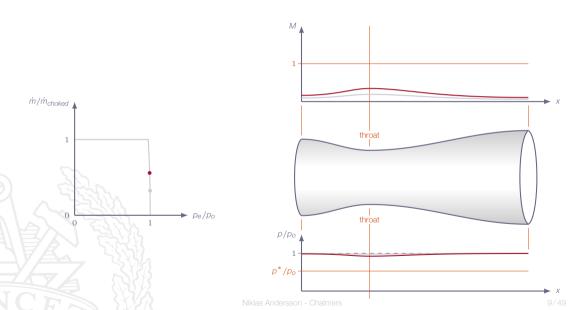


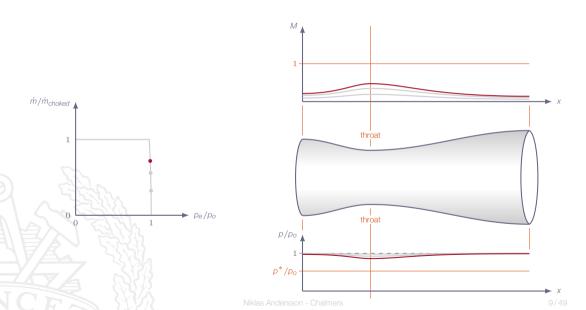
For critical p_0/p_e , a jump to supersonic solution will occur

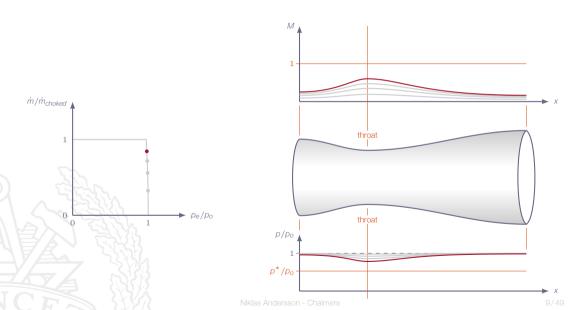


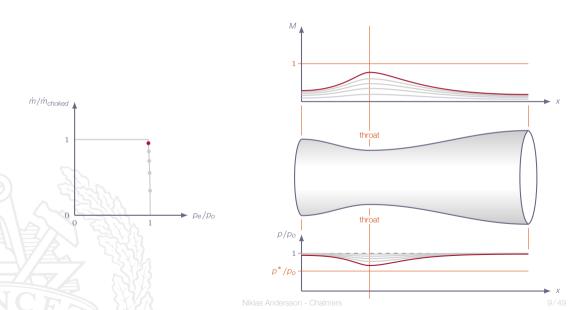
As the flow jumps to the supersonic branch downstream of the throat, a normal shock will appear in order to match the ambient pressure at the nozzle exit

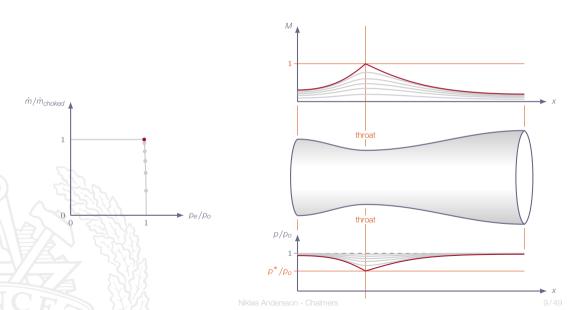


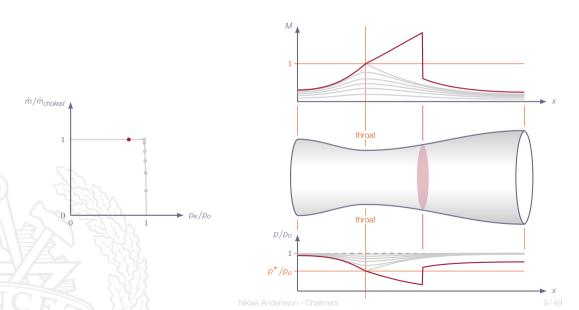


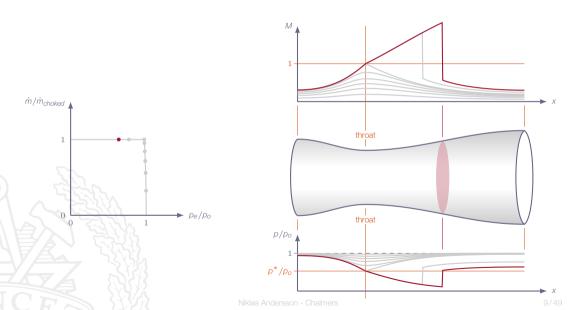


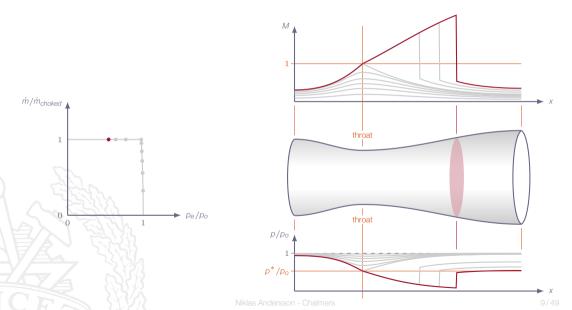


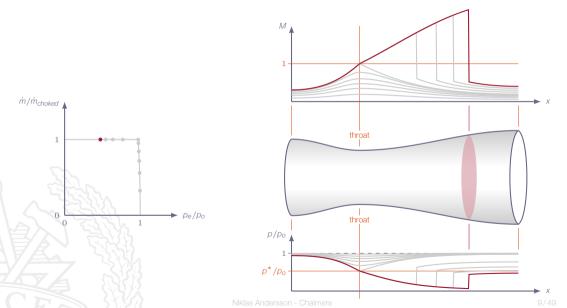


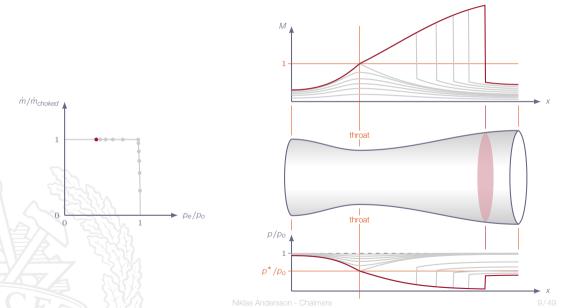


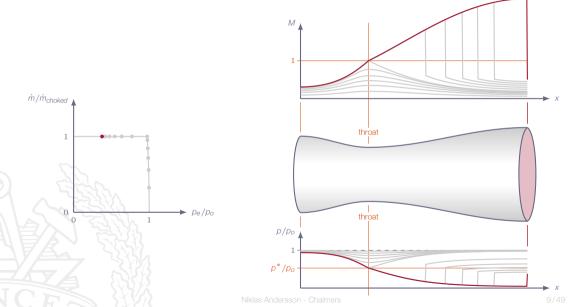


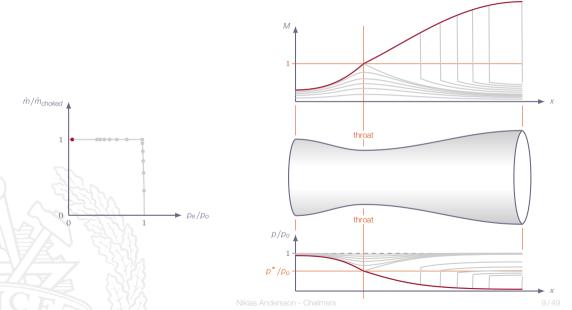












Nozzle Flow with Varying Pressure Ratio (Summary)

$$(p_{o}/p_{e}) < (p_{o}/p_{e})_{cr}$$

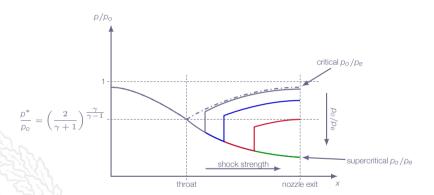
- ► the flow remains entirely subsonic
- \blacktriangleright the mass flow depends on p_e , i.e. the flow is not choked
- no shock is formed, therefore the flow is isentropic throughout the nozzle

$$(p_o/p_e) = (p_o/p_e)_{cr}$$

- ightharpoonup the flow just achieves M=1 at the throat
- the flow will then suddenly flip to the supersonic solution downstream of the throat, for an infinitesimally small increase in (p_o/p_e)

$(p_{o}/p_{e}) > (p_{o}/p_{e})_{cr}$

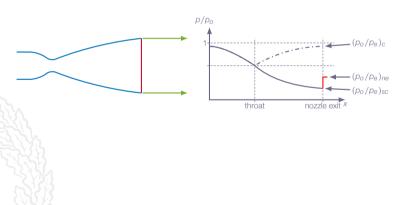
- \blacktriangleright the flow is choked (fixed mass flow), i.e. it does not depend on p_e
- ▶ a normal shock will appear downstream of the throat, with strength and position depending on (p_o/p_e)

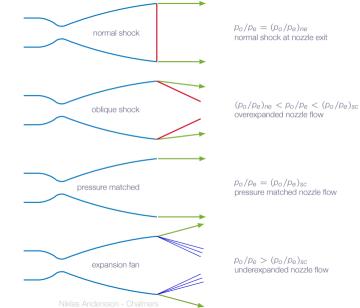


Effects of changing the pressure ratio (p_o/p_e) (where p_e is the back pressure and p_o is the total pressure at the nozzle inlet)

- ightharpoonup critical value: $p_o/p_e = (p_o/p_e)_c$
 - ightharpoonup nozzle flow reaches M=1 at throat, flow becomes choked
- ▶ supercritical value: $p_o/p_e = (p_o/p_e)_{sc}$
 - nozzle flow is supersonic from throat to exit, without any interior normal shock isentropic flow
- normal shock at exit: $(p_o/p_e) = (p_o/p_e)_{ne} < (p_o/p_e)_{sc}$
 - normal shock is still present but is located just at exit isentropic flow inside nozzle

Normal shock at exit





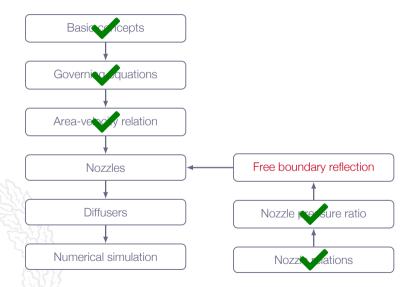
Quasi-one-dimensional theory

- When the interior normal shock is "pushed out" through the exit (by increasing (p_o/p_e) , *i.e.* lowering the back pressure), it disappears completely.
- The flow through the nozzle is then **shock free** (and thus also **isentropic** since we neglect viscosity).

Three-dimensional nozzle flow

- When the interior normal shock is "pushed out" through the exit (by increasing (p_o/p_e)), an oblique shock is formed outside of the nozzle exit.
- For the exact supercritical value of (p_o/p_e) this oblique shock disappears.
- For (p_0/p_e) above the supercritical value an expansion fan is formed at the nozzle exit.

Roadmap - Quasi-One-Dimensional Flow



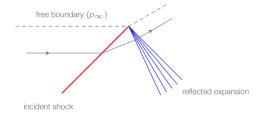
Chapter 5.6 Wave Reflection From a Free Boundary

Free-Boundary Reflection

Free boundary - shear layer, interface between different fluids, etc

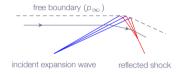


Free-Boundary Reflection - Shock Reflection



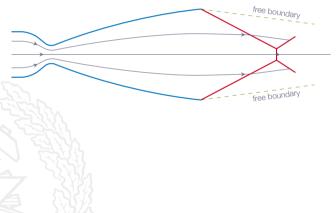
- No jump in pressure at the free boundary possible
- Incident shock reflects as expansion waves at the free boundary
- Reflection results in net turning of the flow

Free-Boundary Reflection - Expansion Wave Reflection

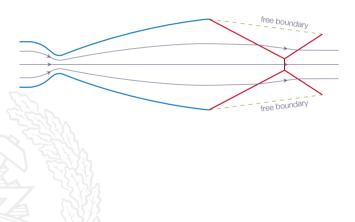


- ► No jump in pressure at the free boundary possible
- Incident expansion waves reflects as compression waves at the free boundary
- Finite compression waves coalesces into a shock
- Reflection results in net turning of the flow

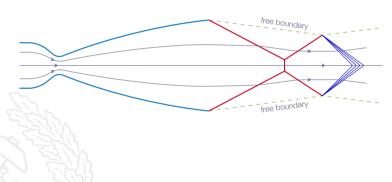
overexpanded nozzle flow



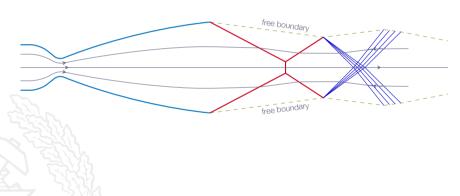
shock reflection at jet centerline



shock reflection at free boundary

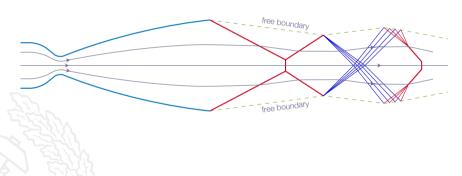


expansion wave reflection at jet centerline



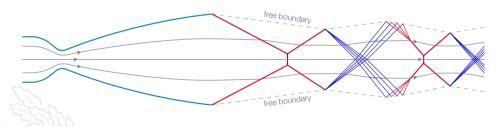
Free-Boundary Reflection - System of Reflections

expansion wave reflection at free boundary



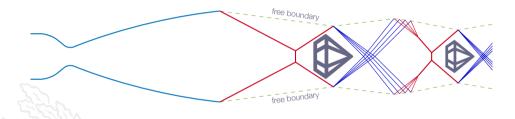
Free-Boundary Reflection - System of Reflections

repeated shock/expansion system



Free-Boundary Reflection - System of Reflections

shock diamonds



Free-Boundary Reflection - Summary

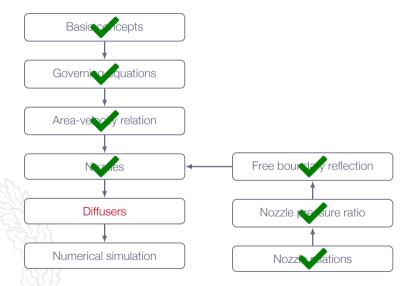
Solid-wall reflection

Compression waves reflects as compression waves Expansion waves reflects as expansion waves

Free-boundary reflection

Compression waves reflects as expansion waves Expansion waves reflects as compression waves

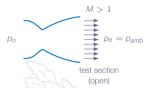
Roadmap - Quasi-One-Dimensional Flow



Chapter 5.5 Diffusers

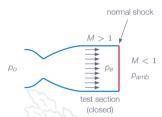


wind tunnel with supersonic test section open test section



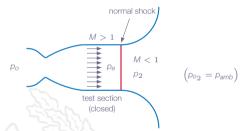
$$p_{\rm O}/p_{\rm e}=(p_{\rm O}/p_{\rm e})_{\rm SC}$$
 $M=3.0$ in test section \Rightarrow $p_{\rm O}/p_{\rm e}=36.7$!!!

wind tunnel with supersonic test section enclosed test section, normal shock at exit



```
p_{\rm o}/p_{\rm amb} = (p_{\rm o}/p_{\rm e})(p_{\rm e}/p_{\rm amb}) < (p_{\rm o}/p_{\rm e})_{\rm SC}
M = 3.0 in test section \Rightarrow
p_{\rm o}/p_{\rm amb} = 36.7/10.33 = 3.55
```

wind tunnel with supersonic test section add subsonic diffuser after normal shock

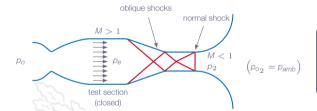


$$p_0/p_{amb} = (p_0/p_e)(p_e/p_2)(p_2/p_{o_2})$$

M = 3.0 in test section \Rightarrow $p_0/p_{amb} = 36.7/10.33/1.17 = 3.04$

Note! this corresponds exactly to total pressure loss across normal shock

wind tunnel with supersonic test section add supersonic diffuser before normal shock

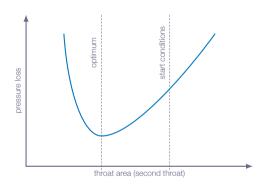


well-designed supersonic + subsonic diffuser \Rightarrow

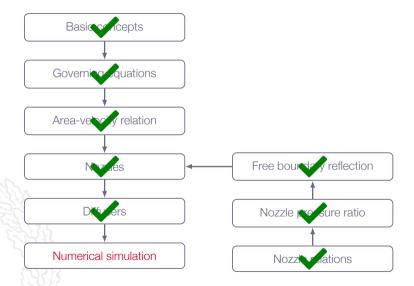
- 1. decreased total pressure loss
- 2. decreased p_0 and power to drive wind tunnel

Main problems:

- 1. Design is extremely difficult due to complex 3D flow in diffuser
 - viscous effects
 - oblique shocks
 - separations
- 2. Starting requirements: second throat must be significantly larger than first throat solution:
 - variable geometry diffuser
 - second throat larger during startup procedure
 - decreased second throat to optimum value after flow is established



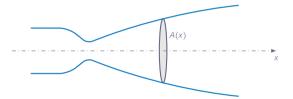
Roadmap - Quasi-One-Dimensional Flow



Quasi-One-Dimensional Euler Equations

Quasi-One-Dimensional Euler Equations

Example: choked flow through a convergent-divergent nozzle



Assumptions: inviscid, Q = Q(x, t)

Quasi-One-Dimensional Euler Equations

$$A(x)\frac{\partial}{\partial t}Q + \frac{\partial}{\partial x}\left[A(x)E\right] = A'(x)H$$

where A(x) is the cross section area and

$$Q = \begin{bmatrix} \rho \\ \rho u \\ \rho e_o \end{bmatrix}, \ E(Q) = \begin{bmatrix} \rho u \\ \rho u^2 + \rho \\ \rho h_o u \end{bmatrix}, \ H(Q) = \begin{bmatrix} 0 \\ \rho \\ 0 \end{bmatrix}$$

Numerical Approach

- ▶ Finite-Volume Method
- ► Method of lines, three-stage Runge-Kutta time stepping
- ► 3rd-order characteristic upwinding scheme
- Subsonic inflow boundary condition at min(x)
 - T_o, p_o given
- Subsonic outflow boundary condition at max(x)
 - p given

Finite-Volume Spatial Discretization

$$\left(\Delta x_{j} = x_{j+\frac{1}{2}} - x_{j-\frac{1}{2}}\right)$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad$$

Integration over cell *i* gives:

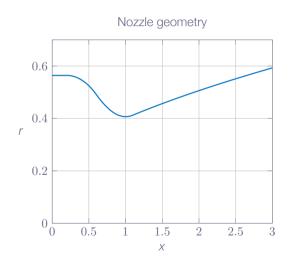
$$\begin{split} \frac{1}{2} \left[A(x_{j-\frac{1}{2}}) + A(x_{j+\frac{1}{2}}) \right] \Delta x_j \frac{d}{dt} \bar{Q}_j + \\ \left[A(x_{j+\frac{1}{2}}) \hat{E}_{j+\frac{1}{2}} - A(x_{j-\frac{1}{2}}) \hat{E}_{j-\frac{1}{2}} \right] = \\ \left[A(x_{j+\frac{1}{2}}) - A(x_{j-\frac{1}{2}}) \right] \hat{H}_j \end{split}$$

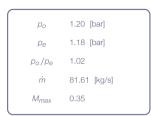
Finite-Volume Spatial Discretization

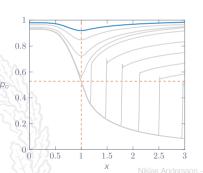
$$\bar{Q}_{j} = \left(\int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} QA(x) dx \right) / \left(\int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} A(x) dx \right)$$

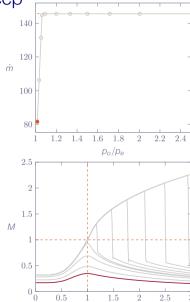
$$\hat{E}_{j+\frac{1}{2}} \approx E\left(Q\left(X_{j+\frac{1}{2}}\right)\right)$$

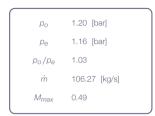
$$\hat{H}_{j} \approx \left(\int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} HA'(x) dx \right) / \left(\int_{x_{j-\frac{1}{2}}}^{x_{j+\frac{1}{2}}} A'(x) dx \right)$$

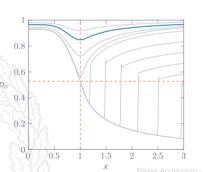


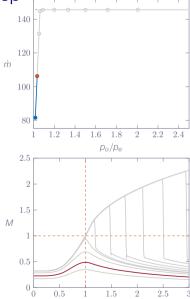


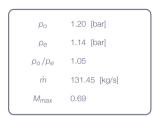


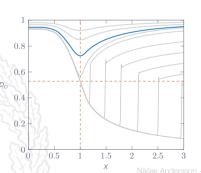


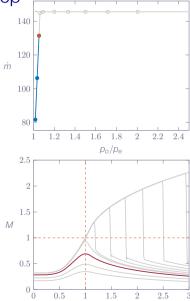


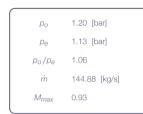


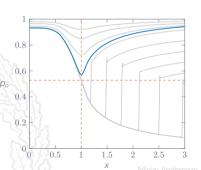


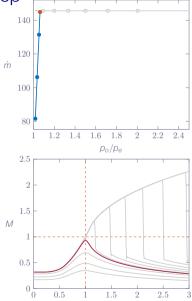


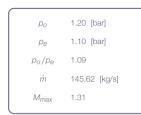


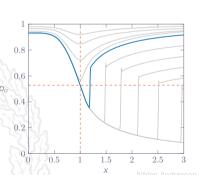


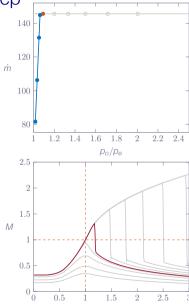


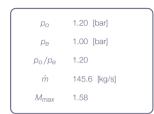


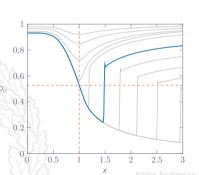


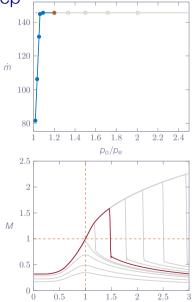


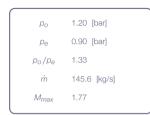


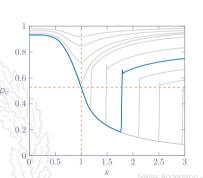


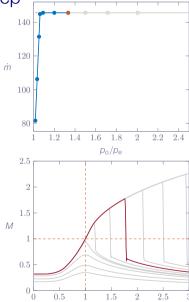


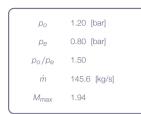


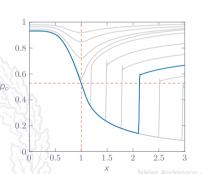


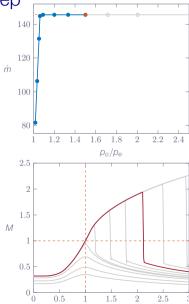


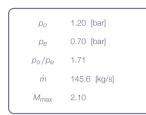


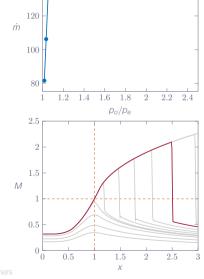




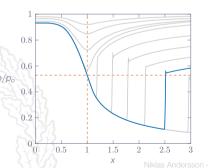


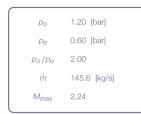


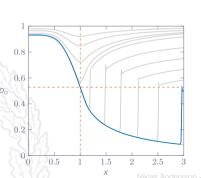


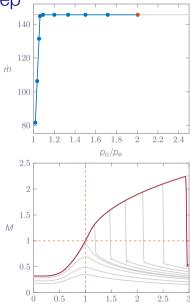


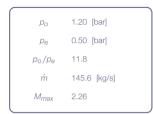
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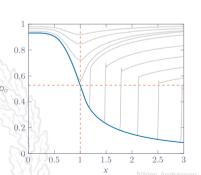


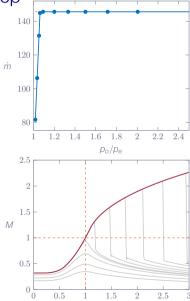


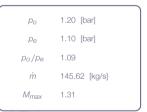


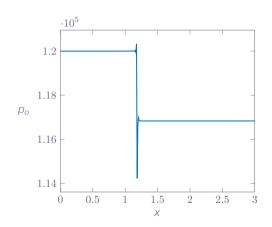


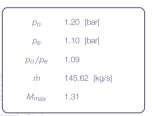


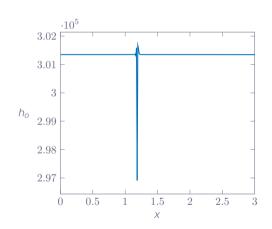












Roadmap - Quasi-One-Dimensional Flow

